

| | | |
|--|---------------------------|--------------------------------------|
| Last Modified: 12-04-2024 | 6.11:8.1.0 | Doc ID: RM100000028X25 |
| Model Year Start: 2023 | Model: Prius Prime | Prod Date Range: [12/2022 -] |
| Title: BRAKE CONTROL / DYNAMIC CONTROL SYSTEMS: ELECTRONICALLY CONTROLLED BRAKE SYSTEM: C13BA2B; Electronic Brake Booster Motor "A" Current Sensor Signal Cross Coupled ; 2023 - 2024 MY Prius Prius Prime [12/2022 -] | | |

| | | |
|------------|----------------|---|
| DTC | C13BA2B | Electronic Brake Booster Motor "A" Current Sensor Signal Cross Coupled |
|------------|----------------|---|

DESCRIPTION

The No. 1 skid control ECU (brake booster with master cylinder assembly) uses the motor current monitor circuit to monitor the three-phase current.

| DTC NO. | DETECTION ITEM | DTC DETECTION CONDITION | TROUBLE AREA | MIL | DTC OUTPUT FROM | PRIORITY | NOTE |
|---------|--|--|--|----------|-----------------|----------|---|
| C13BA2B | Electronic Brake Booster Motor "A" Current Sensor Signal Cross Coupled | When three-phase current malfunction status continues. | No. 1 skid control ECU (brake booster with master cylinder assembly) | Comes on | Brake/EPB | A | <ul style="list-style-type: none"> SAE Code: C13BB Output ECU: Both skid control ECUs |

MONITOR DESCRIPTION

Case 1:

The pump motor is built into the No. 1 skid control ECU (brake booster with master cylinder assembly).

With the vehicle power source voltage normal, voltage applied normally to the motor power source terminal and the No. 1 skid control ECU (brake booster with master cylinder assembly) started, if the current monitor U, V or W phase current value continues to be abnormally high or repeatedly switches between abnormally high and normal, the No. 2 skid control ECU (brake actuator assembly) determines that there is a pump motor drive circuit malfunction, the MIL is illuminated and a DTC is stored.

Case 2:

The pump motor is built into the No. 1 skid control ECU (brake booster with master cylinder assembly).

With voltage applied normally to the motor power source terminal and the motor stopped (current not flowing) during the ECU self-check immediately before the No. 1 skid control ECU (brake booster with master cylinder assembly) stops, if the current monitor value is the value during motor operation (current is flowing), the No. 2 skid control ECU (brake actuator assembly) determines that there is a pump motor drive circuit malfunction, the MIL is illuminated and a DTC is stored.

MONITOR STRATEGY

| | |
|--------------|---|
| Related DTCs | C13BB (Case 1): Brake booster motor range/performance |
|--------------|---|

| | |
|--------------------------------------|---|
| Required Sensors/Components(Main) | No. 2 skid control ECU (brake actuator assembly) Brake booster with master cylinder assembly |
| Required Sensors/Components(Related) | - |
| Frequency of Operation | Continuous |
| Duration | 0.072 seconds: Case 2 -: Case 1 |
| MIL Operation | Immediately |
| Sequence of Operation | None |

TYPICAL ENABLING CONDITIONS

Case 1

| | |
|---|---|
| Monitor runs whenever the following DTCs are not stored | C129B: Rotation angle sensor range/performance C12B4 (Case 2): Brake booster motor performance (motor current) C12BF (Case 1 to 4): Brake booster motor performance (motor upper circuit) C12BF (Case 5 to 9): Brake booster motor performance (motor drive circuit) C14C8: Brake system voltage circuit high |
| All of the following conditions are met | A, B, C, D or E |
| A. Both of the following conditions are met | More than 0.198 seconds |
| +BS cut MOS | Valid |
| +BS cut MOS voltage | Below 23.2 V |
| B. Both of the following conditions are met | More than 0.198 seconds |
| +BS cut MOS | Valid |
| +BS cut MOS voltage | Higher than 7.4 V |
| C. Following condition is met | More than 0.198 seconds |
| BM voltage | 7.1 V or higher |
| D. Command to motor failsafe relay | On |
| E. +BS cut MOS voltage | Higher than 7.8 V |

Case 2

| | |
|---|-------------|
| Monitor runs whenever the following DTCs are not stored | None |
| Both of the following conditions are met | A and B |
| A. Both of the following conditions are met | - |
| ECU status | Remain |
| ECU status | Final check |
| B. Inverter drive signal | Off |

TYPICAL MALFUNCTION THRESHOLDS

Case 1

| | |
|--|-------------------------|
| Either of the following conditions is met | A or B |
| A. Following condition is met | More than 0.072 seconds |
| Absolute value of the sum of U-phase current, V-phase current, and W-phase current | Higher than 35 A |
| B. Motor current monitor Valid to Invalid edge count | More than 10 times |

Case 2

| | |
|---|-------------------------------|
| Either of the following conditions is met | - |
| SO1 voltage monitor | 2 V or less, or 3 V or higher |
| SO2 voltage monitor | 2 V or less, or 3 V or higher |
| SO3 voltage monitor | 2 V or less, or 3 V or higher |

COMPONENT OPERATING RANGE

All

| | |
|--|-------------------------|
| Either of the following conditions is met | A, B, C, D or E |
| A. All of the following conditions are met | a, b, c, d and e |
| a. Both of the following conditions are met | More than 0.198 seconds |
| +BS cut MOS | Valid |
| +BS cut MOS voltage | Below 23.2 V |
| b. Both of the following conditions are met | More than 0.198 seconds |
| +BS cut MOS | Valid |
| +BS cut MOS voltage | Higher than 7.4 V |
| c. Following condition is met | More than 0.198 seconds |
| BM voltage | 7.1 V or higher |
| d. Command to motor failsafe relay | On |
| e. Both of the following conditions are met | 1 and 2 |
| 1. Following condition is met | More than 1 second |
| Absolute value of the sum of U-phase current, V-phase current, and W-phase current | 35 A or less |
| 2. Following condition is met | More than 1 second |
| Motor current monitor Valid to Invalid edge count | 0 times |
| B. All of the following conditions are met | a, b and c |
| a. Either of the following conditions is met | - |
| ECU status | Remain |
| ECU status | Final check |

| | |
|--|--------------------------------|
| b. Inverter drive signal | Off |
| c. All of the following conditions are met | - |
| SO1 voltage monitor | Higher than 2 V, and below 3 V |
| SO2 voltage monitor | Higher than 2 V, and below 3 V |
| SO3 voltage monitor | Higher than 2 V, and below 3 V |

CONFIRMATION DRIVING PATTERN

NOTICE:

When performing the normal judgment procedure, make sure that the driver door is closed and is not opened at any time during the procedure.

HINT:

- After repair has been completed, clear the DTC and then check that the vehicle has returned to normal by performing the following All Readiness check procedure.
- When clearing the permanent DTCs, refer to the "CLEAR PERMANENT DTC" procedure.

1. Connect the GTS to the DLC3.
2. Turn the ignition switch to ON and turn the GTS on.
3. Clear the DTCs (even if no DTCs are stored, perform the clear DTC procedure).
4. Turn the ignition switch off.
5. Turn the ignition switch to ON (READY) and turn the GTS on.
6. Wait for 2 seconds or more. [*]

HINT:

[*]: Normal judgment procedure.

The normal judgment procedure is used to complete DTC judgment and also used when clearing permanent DTCs.

7. Enter the following menus: Chassis / Brake/EPB* / Utility / All Readiness.

*: Electric Parking Brake System

8. Check the DTC judgment result.

HINT:

- If the judgment result shows NORMAL, the system is normal.
- If the judgment result shows ABNORMAL, the system has a malfunction.
- If the judgment result shows INCOMPLETE, perform driving pattern again.

PROCEDURE

1. REPLACE BRAKE BOOSTER WITH MASTER CYLINDER ASSEMBLY

HINT:

Click here [INFO](#)

NEXT  **END**

